

# Adaptive Hedge

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## SUMMARY

AdaHedge is a new online learning algorithm that adapts to the difficulty of the data

Difficulty	Regret
Worst-case data	$O(\sqrt{L_T^* \ln(K)})$
Easy data	constant: $O(K)$

### Key Ideas

- Bounds on the *mixability gap* (see top-right panel) play a crucial role in previous analyses of the Hedge algorithm.
- We only bound the mixability gap in the analysis, but not in the algorithm!
- On easy data, the probabilities output by Hedge converge on a single action. In this case we improve the standard bounds.
- Example: if one action is always better than all others.

## ONLINE LEARNING SETTING

### Decision Theoretic Online Learning

In rounds  $t = 1, \dots, T$ :

1. Assign probabilities  $w_t = (w_t^1, \dots, w_t^K)$  to  $K$  actions
2. Actions get losses  $\ell_t \in [0, 1]^K$
3. Our loss:  $w_t \cdot \ell_t$

Aim to minimize the *regret*

$$R(T) = \sum_{t=1}^T w_t \cdot \ell_t - L_T^*,$$

where  $L_T^* = \min_k \sum_{t=1}^T \ell_t^k$  is the loss of the best action in hindsight.

## HEDGE

- Hedge predicts with exponential weights:

$$w_t^k \propto \exp\left(-\eta \sum_{s=1}^{t-1} \ell_s^k\right).$$

- Its performance depends strongly on the *learning rate*  $\eta > 0$ .

## MIXABILITY GAP

The *mixability gap* is

$$\delta_t(\eta) = w_t \cdot \ell_t - \left(-\frac{1}{\eta} \ln(w_t \cdot e^{-\eta \ell_t})\right).$$

- In Prediction with Expert Advice terms:  $\delta_t(\eta)$  measures the difference with a mixable loss function.
- In Bayesian terms:  $\delta_t(\eta)$  measures the difference between randomizing according to the posterior and mixing according to the posterior.

## ADAHEDGE

- Tune  $\eta$  optimally for a budget  $b(\eta)$  on the cumulative mixability gap  $\Delta_T(\eta) = \sum_{t=1}^T \delta_t(\eta)$
- Increase the budget using the doubling trick.

### Algorithm

1. Start with  $\eta = 1$
2. Run a new instance of Hedge with learning rate  $\eta$  until  $\Delta_T(\eta)$  exceeds budget
 
$$b(\eta) = \left(\frac{1}{\eta} + \frac{1}{e-1}\right) \ln(K).$$
3. Set  $\eta \leftarrow \eta/2$  and goto 2.

## THEORETICAL RESULTS

AdaHedge is worst-case optimal...

**Theorem 1** The regret of AdaHedge is bounded by

$$R(T) \leq 5.1 \sqrt{L_T^* \ln(K)} + O(\ln(L_T^* + 2) \ln(K)).$$

...and has strong theoretical guarantees on 'easy' data

**Theorem 2** Suppose the loss vectors  $\ell_t$  are independent random variables and there exists a  $k^*$  such that

$$\min_{k \neq k^*} \mathbb{E}[\ell_t^k - \ell_t^{k^*}] > 0 \quad \text{for all } t \in \mathbb{Z}^+.$$

Then with probability at least  $1 - \delta$  the regret of AdaHedge is bounded by a constant:

$$R(T) = O(K + \log(1/\delta)).$$

## PROOF TECHNIQUES

Everyone bounds the mixability gap  $\delta_t$ .

### Standard Analysis

- Optimize  $\eta$  after bounding  $\delta_t(\eta) \leq \eta/8$ .

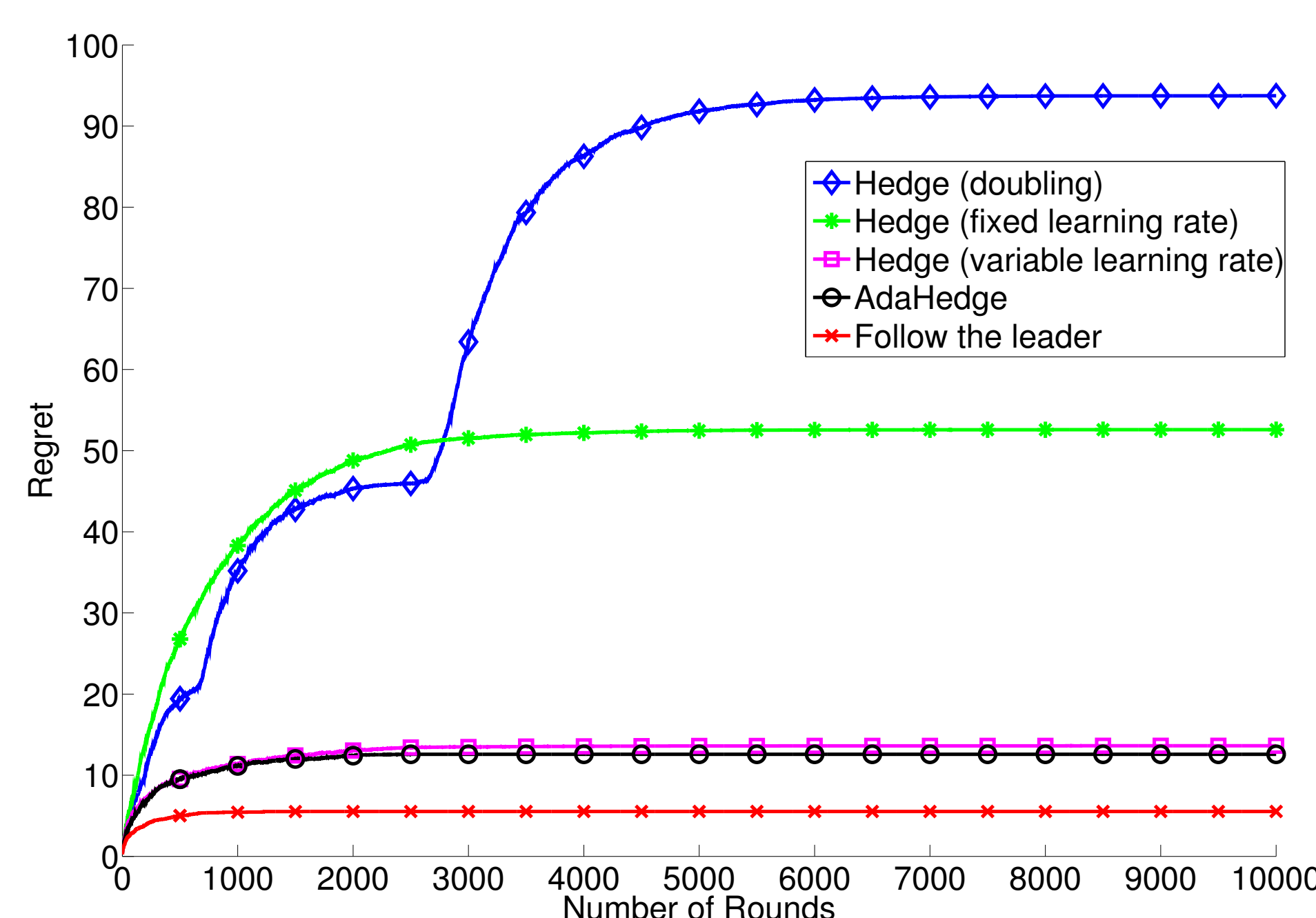
### Our Approach

- Optimize  $\eta$  before bounding!
- If the posterior probabilities  $w_t$  converge on a single action, the mixability gap goes to 0!

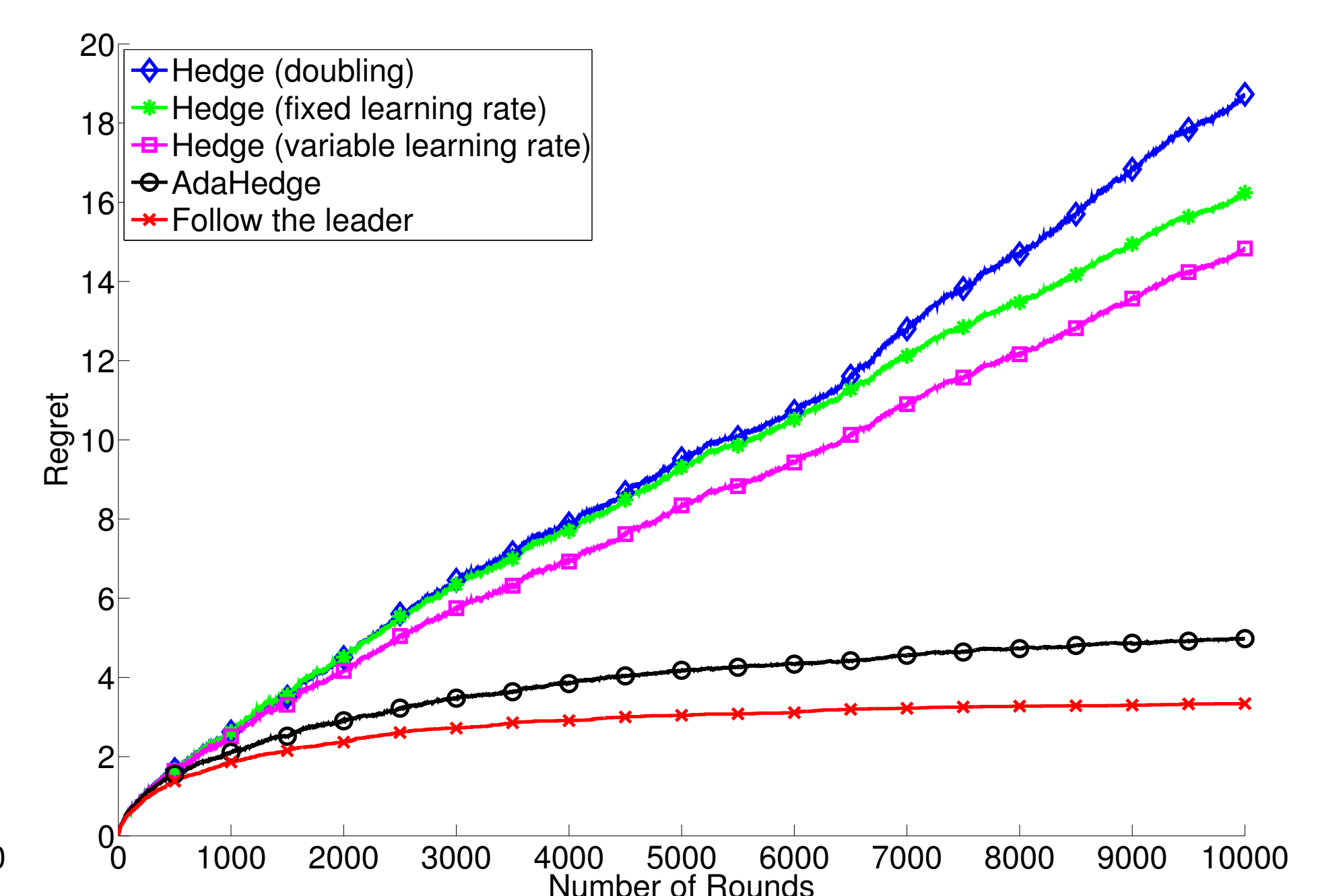
$$\delta_t(\eta) \leq (e-2)\eta(1 - \max_k w_t^k) \quad (0 < \eta \leq 1)$$

## EXPERIMENTS

### Simulation Study on 'Easy' Data



I.I.D. losses



Correlated losses

AdaHedge has excellent practical performance

N.B. Follow-the-leader does very well here, but gets *linear* regret  $\geq T/2 - 1$  in the worst case!

## CURRENT WORK

### Avoid the Doubling Trick

- Better performance in practice
- Still very clean analysis
- Improved the worst-case bound to

$$R(T) \leq 2\sqrt{\frac{L_T^*(T - L_T^*)}{T} \ln(K)} + \frac{8}{3} \ln(K) + 2.$$

### Weaker Conditions for Easy Data

- Guarantee regret bounded by the best *regret* of AdaHedge and Follow-the-Leader, up to a small constant factor.

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